

# **GMM ESTIMATION AND TESTING OF ASSET PRICING MODELS**

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## 9.0 INTRODUCTION

Suppose

$$m_{t+1} = \beta(C_{t+1} / C_t)^{-\gamma}$$

$$m_{t+1} = \mathbf{b}' \mathbf{f}_{t+1}$$

How do we estimate the parameters  $\beta$  and  $\gamma$  or the vector  $\mathbf{b}$ ?

Asset pricing model predicts:

$$E_t p_t = E_t m(\text{data}_{t+1}, \text{parameters}) x_{t+1}$$

This statement also holds unconditionally, so let us consider sample equivalent:

$$\frac{1}{T} \sum_{t=1}^T P_t = \frac{1}{T} \sum_{t=1}^T [m(\text{data}_{t+1}, \text{par}) x_{t+1}]$$

- GMM estimates the parameters by making these two sample means as close to each other as possible.
- GMM tests model by appraising how close sample means are.
- GMM versus MLE

### Basic references

- Hansen (1982)
- Hansen and Singleton (1982)
- Hall (1992, 1999)
- Ogaki (1992)
- Matyas (1999)

# 9.1 GMM IN EXPLICIT DISCOUNT FACTOR MODELS

Approach popularized by Hansen and Singleton (1982).

Write discount factor as:

$$m_{t+1}(b)$$

For example:

$$m_{t+1}(b) = \beta (C_{t+1} / C_t)^{-\gamma}$$

$$b \equiv (\beta\gamma)'$$

Then

$$E_t p_t = E_t m_{t+1}(b) x_{t+1}$$
$$E_t (m_{t+1}(b) x_{t+1} - p_t) = 0$$

Define Errors

$$u_t(b) = m_{t+1}(b) x_{t+1} - p_t$$

Define Sample Mean

$$g_T(b) = \frac{1}{T} \sum_{t=1}^T u_t(b)$$

# FORECAST ERRORS

$$u_{t+1} = m_{t+1}R_{t+1} - 1$$

Instrument orthogonal to  $u_{t+1}$

$$EZ_t u_{t+1} = 0$$

Pricing Errors:

Consider Moment Conditions

$$g(b) = E[m_{t+1}(b)x_{t+1} - p_t]$$

$$E(m_{t+1}(b)x_{t+1}) - Ep_t$$

Is Pricing Error Diff. Model and Obs. Prices