

# Global Existence of Solutions to Multiple Speed Systems of Quasilinear Wave Equations in Exterior Domains

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## Outline

- ◆ The Beginnings... the results of Klainerman and Christodolou.
- ◆ Multiple Speed Wave Equations in Free Space.
- ◆ Wave Equations in Exterior Domains.
- ◆ Two New Results: M.-Sogge, M.-Nakamura-Sogge

## The Wave Equation

$$\square u^I(t, x) = (\partial_t^2 - \Delta) u^I(t, x) = Q^I(du, d^2u)$$

$$(1) \quad u(0, x) = f(x); \quad \partial_t u(0, x) = g(x)$$

$$(t, x) \in R_+ \times R^3 \quad I = 1, 2, \dots, D$$

$$u = (u^1, u^2, \dots, u^D)$$

## The Nonlinearity

- ◆ Vanishes to Second Order
- ◆ Linear in  $d^2u$

$$Q^I(du, d^2u) = \sum_{\substack{0 \leq j, k, l \leq 3 \\ 1 \leq J, K \leq D}} B_{K,l}^{I,jk} \partial_l u^K \partial_j \partial_k u^J$$

- ◆ Symmetry:  $B_{K,l}^{I,jk} = B_{K,l}^{I,jk} = B_{K,l}^{I,kj}$
- ◆ We can also allow similar semilinear terms.

## Applications

- ◆ Such wave equations come up in a number of applications. For example, the previously stated wave equation is closely related to geometric wave maps.
- ◆ In the multiple speed case that we will discuss soon, they are related to the equations of elasticity, charged plasma, and magneto-hydrodynamics.

## Long Time Solutions

- ◆ Well established local existence theory.
- ◆ When does (1) admit a global solution for "small"  $f, g$ ?
- ◆ If  $n \geq 4$ , the Cauchy problem (1) has a global solution. [Klainerman, Hörmander (~1985)]

## Klainerman-Sobolev Inequality

- ◆What happens when  $n=3$ ?
- ◆Klainerman-Sobolev Inequality:

$$(1+t+|x|)^{(n-1)/2} (1+|t-|x||)^{1/2} |u(t,x)| \leq C \sum_{|\alpha| \leq \frac{n+2}{2}} \|\Gamma^\alpha u(t,\cdot)\|_2$$

- ◆The solution has  $O(t^{-1})$  decay. Not quite integrable.

## Almost Global Existence

- ◆In  $n=3$ , there is almost global existence. That is, as  $f, g$  get smaller, the lifespan of the solution grows exponentially. [John-Klainerman (1984)]
- ◆The following example always blows up in finite time in  $n=3$ . [John (1981)]

$$\square u = (\partial_t u)^2$$

## Null Condition

- ◆The following example has a global solution in  $n=3$  for sufficiently small data. [Nirenberg]

$$\square u = (\partial_t u)^2 - \sum_{j=1}^3 (\partial_j u)^2$$

- ◆We want to put an extra condition on the quadratic part of the nonlinearity, the null condition.

## Null Condition

- ◆We want to limit the amount of the nonlinearity in the "bad" direction.
- ◆In the scalar valued, semilinear case, the null condition says that the nonlinearity must be a constant multiple of the one in Nirenberg's example.

## Null Condition

- ◆More generally, in the current case, we require

$$\sum_{J,K=1}^D \sum_{j,k,l=0}^3 B_{K,l}^{J,jk} \xi_j \xi_k \xi_l = 0$$

whenever

$$\xi_0^2 = \xi_1^2 + \xi_2^2 + \xi_3^2$$

## Global Existence in $n=3$

- ◆Suppose  $n=3$  and suppose further that the nonlinearity  $Q$  satisfies the null condition. Then, (1) has a global solution for "small"  $f, g$ . [Klainerman, Christodolou (1986)]

## Christodolou's Method

- ◆ Uses the Penrose conformal compactification of Minkowski space.
- ◆ A hyperbolic space analog of stereographic projection. Also, related to the Kelvin transformation (inversion about a sphere).

## Christodolou's Method (2)

- ◆ Map space-time conformally to the Einstein diamond,
 
$$\{(T, X) \in (-\pi, \pi) \times S^3 : |T| + R < \pi\}$$

$$R = \arctan(t+r) - \arctan(t-r)$$

$$T = \arctan(t+r) + \arctan(t-r)$$
- ◆ Use local existence theory to get a solution on this compact space.

## Klainerman's Method

- ◆ Method of commuting vector fields.
- ◆ Continuity argument (a continuous version of induction).
- ◆ The Invariant Vector Fields
 
$$\Gamma = \{\partial_t, \partial_k, \Omega_{0k}, \Omega_{ij}, L\}$$

$$1 \leq k \leq 3, 1 \leq i < j \leq 3$$

## Invariant Vector Fields

- ◆ Spatial Rotations
 
$$\Omega_{ij} = x_i \partial_j - x_j \partial_i$$
- ◆ Hyperbolic Rotations
 
$$\Omega_{0k} = t \partial_k + x_k \partial_t$$
- ◆ Scaling
 
$$L = t \partial_t + r \partial_r$$

## Invariant Vector Fields (2)

- ◆ All of the vector fields preserve the equation  $\square u = 0$
- ◆ Generators of the Poincaré group.
- ◆ Using these, we want to set up a continuity argument. In this case, it is a coupling between a dispersive estimate and an energy estimate.

## Continuity Argument

$$\sum_{|\alpha| \leq k} |\Gamma^\alpha u(t, x)| \leq \frac{A\epsilon}{(1+t+|x|)}$$

$$\sum_{|\alpha| \leq k+3} \|\Gamma^\alpha u'(t, \cdot)\|_2 \leq C_1 (1+t)^{C_0 \epsilon} \sum_{|\alpha| \leq k+3} \|\Gamma^\alpha u'(0, \cdot)\|_2$$

## The Continuity Argument (2)

- ◆ There are two basic steps:
  - Show that the energy estimate follows from the pointwise estimate.
  - Show that the pointwise estimate with  $A$  replaced by  $A/2$  under the assumption of the energy estimate and the pointwise estimate.
- ◆ In order to accomplish the latter, we must use the extra decay that follows from the null condition.

## Decay from the Null Condition

$$\sum_{|\alpha| \leq M} |\Gamma^\alpha Q(v, w)| \leq \frac{C_M}{(1+t+|x|)} \sum_{1 \leq |\alpha| \leq M+1} |\Gamma^\alpha v| \cdot \sum_{1 \leq |\alpha| \leq (M+2)/2} |\Gamma^\alpha w|$$

$$+ \frac{C_M}{(1+t+|x|)} \sum_{1 \leq |\alpha| \leq (M+2)/2} |\Gamma^\alpha v| \cdot \sum_{1 \leq |\alpha| \leq M+1} |\Gamma^\alpha w|$$

## Nonrelativistic Multiple Speed Systems

□ <sub>$c_1$</sub>   $u^I(t, x) = (\partial_t^2 - c_1^2 \Delta) u^I(t, x) = Q^I(du, d^2u)$

(2)  $u(0, x) = f(x); \quad \partial_t u(0, x) = g(x)$

$(t, x) \in R_+ \times R^3 \quad I = 1, 2, \dots, D$

$u = (u^1, u^2, \dots, u^D)$

$0 < c_D < \dots < c_1$

## Two Null Conditions

(N1)  $\sum_{J=1}^D \sum_{j,k,l=0}^3 B_{J,l}^{J,j,k} \xi_j \xi_k \xi_l = 0$  whenever

$$\frac{\xi_0^2}{c_J^2} = \xi_1^2 + \xi_2^2 + \xi_3^2$$

(N2)  $\sum_{J=1}^D \sum_{j,k,l=0}^3 B_{J,l}^{J,j,k} \xi_j \xi_k \xi_l = 0$  whenever

$$\frac{\xi_0^2}{c_J^2} = \xi_1^2 + \xi_2^2 + \xi_3^2$$

## New Challenge

- ◆ The generators of the hyperbolic rotations  $\Omega_{0k}$  have an associated wave speed, and thus do not seem appropriate for this setting.
- ◆ Denote, now,
 
$$Z = \{\partial_t, \partial_k, \Omega_{ij}\}, \quad 1 \leq k \leq 3, \quad 1 \leq i < j \leq 3$$

$$\Gamma = \{Z, L\}$$

## Decay from the Null Condition

- ◆ In case of (N1) or (N2), we get the following additional decay:

$$\left| \sum_{0 \leq j,k,l \leq 3} B_{j,l}^{J,j,k} \partial_l u \partial_j \partial_k u \right| \leq C \langle r \rangle^{-1} \left( |\Gamma u| |\partial^2 v| + |\partial u| |\partial \Gamma v| \right)$$

$$+ C \frac{\langle c_j t - r \rangle}{\langle t + r \rangle} |\partial u| |\partial^2 v|$$

## Existence Results for (2)

- ◆ Almost Global Existence [Klainerman-Sideris 1996]
- ◆ Global Existence with Null Condition (N1) [Sideris 2000, Sogge 2001]
- ◆ Global Existence with Null Condition (N2) [Agemi-Yokoyama 1998, Kubota-Yokoyama 2001, Sideris-Tu 2001]

## Sideris-Tu Argument

- ◆ Rather than using a coupling of a pointwise estimate with a higher order energy estimate, they couple two energy inequalities.
- ◆ By doing so, they are able to avoid direct estimation of the fundamental solution for the linear wave equation.

## The Exterior Domain

- ◆ We want to look at existence exterior to a compact set with smooth boundary (an obstacle).

$$K \subset \{x \mid x \ll D\} \subset R^n$$

$$\Omega = R^n \setminus K$$

## The Dirichlet Problem

$$\square u^I(t, x) = (\partial_t^2 - \Delta) u^I(t, x) = Q^I(du, d^2u)$$

$$(3) \quad u(0, x) = f(x); \quad \partial_t u(0, x) = g(x)$$

$$u(t, x) = 0 \quad \text{when } x \in \partial K$$

$$(t, x) \in R_+ \times \Omega \quad I = 1, 2, \dots, D$$

$$u = (u^1, u^2, \dots, u^D)$$

## Existence results for (3)

- ◆ If we assume the null condition, there is a global solution to (3) if the obstacle is star-shaped and  $f, g$  are sufficiently small. [Keel-Smith-Sogge 2002]
- ◆ They also establish the local existence theory in the exterior domain.
- ◆ As in Christodolou, they conformally map  $R_+ \times \Omega$  to the Einstein diamond.

## The Nonrelativistic Dirichlet Problem

$$\square u^I(t, x) = (\partial_t^2 - c_I^2 \Delta) u^I(t, x) = Q^I(du, d^2u)$$

$$(4) \quad u(0, x) = f(x); \quad \partial_t u(0, x) = g(x)$$

$$u(t, x) = 0 \quad \text{when } x \in \partial K$$

$$(t, x) \in R_+ \times \Omega \quad I = 1, 2, \dots, D$$

$$u = (u^1, u^2, \dots, u^D) \quad 0 < c_D < \dots < c_1$$

## New Challenges

- ◆ The invariant vector fields do not preserve the Dirichlet conditions.
- ◆ The coefficients of  $Z$  remain small in a neighborhood of our (compact) obstacle. The coefficients of the scaling vector field however can grow large in a small neighborhood of the obstacle.
- ◆ No strong Huygen's principle.

## Almost Global Existence to (4)

- ◆ There are almost global solutions to (4) for sufficiently small data  $f, g$  if the obstacle is star-shaped. [Keel-Smith-Sogge 2003]

## Keel-Smith-Sogge Argument

- ◆ Rather than relying on the  $O(t^{-1})$  decay that one obtains from the Klainerman-Sobolev inequality, they exploit the decay that follows from

$$\|h\|_{L^\infty(R/2 < |x| < R)} \leq CR^{-1} \sum_{|\alpha|+|\beta| \leq 2} \|\Omega^\alpha \partial^\beta h\|_{L^2(R/4 < |x| < 2R)}$$

## Keel-Smith-Sogge Argument

- ◆ To utilize this decay and to handle certain boundary terms that necessary arise when working with obstacles, KSS use a class of weighted  $L^2 L^2(\langle x \rangle^{-1/2} dt dx)$  estimates. They are exterior domains analogs of

$$\|\langle x \rangle^{-1/2} v\|_{L^2 L^2_{\langle x \rangle}(0, T) \times \mathbb{R}^3} \leq C(\ln(2+t))^{1/2} \int_0^T \|\square v(s, \cdot)\| ds$$

## More on Exterior Domains...

- ◆ We want to look at global existence results for multiple speed systems in more general exterior domains.
- ◆ We want to look at domains with a smooth, compact (but not necessarily connected) obstacle.
- ◆ Our only other assumption is...

## Exponential Local Energy Decay

- ◆ If  $u$  is a solution to  $\square u = 0$  with data  $f, g$  supported in  $\{|x| < D\}$ , then

$$(E) \quad \|u'(t, \cdot)\|_{L^2(B_D)} \leq C e^{-ct} \sum_{|\alpha| \leq 1} \|\partial_x^\alpha u'(0, \cdot)\|_2$$

where

$$B_D = \{|x| < D\} \cap \Omega$$

- ◆ We could allow for more "loss" on the right. By interpolation, (E) holds WLOG

## Exponential Local Energy Decay

- ◆ An inequality stronger than (E) holds for any nontrapping obstacle. [e.g. Morawetz-Ralston-Strauss (1977)]
- ◆ If there are trapped rays, you must allow for some loss of derivative. [Ralston (1969)]
- ◆ (E) holds in the exterior of several convex bodies with separation [Ikawa (1998)]

## Exponential Local Energy Decay

- ◆ In any exterior domain, if you allow a loss of  $k$  derivatives on the right side, the local energy is  $O((\log(2+t))^{-k})$ . [Burq (1998)]
  - This does not seem sufficient for our results. Since this result allows elliptic trapped rays, it seems doubtful that global existence results could hold in this setting.
- ◆ We don't actually need exponential decay.

## Global Existence for (4)

- ◆ Suppose that the local energy decay estimate (E) holds and that the null condition (N1) holds. Then, there is a global solution to (4) for sufficiently small data  $f, g$ . [M.-Sogge (2003)]

## Simplifying Assumptions

- ◆ By scaling, we may assume  $D=1$ .
- ◆ Using the local existence theory, we can assume that  $f, g$  vanish and that  $Q$  is supported  $|x| < 10t$ 
  - This assumption also allows us to ignore the necessary compatibility conditions on the data  $f, g$ .

## The Continuity Argument

$$\frac{(1+t+|x|) \sum_{|\alpha| \leq 40} |Z^\alpha u(t, x)| \leq A_0 \varepsilon}{(1+t+|x|) \sum_{|\alpha|+v \leq 55, v \leq 2} \|L^v Z^\alpha u(t, x)\| \leq B_1 \varepsilon (1+t)^{1/5} \log(2+t)}$$

$$\sum_{|\alpha| \leq 100} \|\partial^\alpha u'(t, \cdot)\|_2 \leq B_2 \varepsilon (1+t)^{1/20}$$

$$\sum_{|\alpha|+v \leq 70, v \leq 3} \|L^v Z^\alpha u'(t, \cdot)\|_2 \leq B_3 \varepsilon (1+t)^{1/10}$$

$$\sum_{|\alpha|+v \leq 68, v \leq 3} \left\| \langle x \rangle^{-1/2} L^v Z^\alpha u \right\|_{L^2 L^2(S_t)} \leq B_4 \varepsilon (1+t)^{1/10} (\log(2+t))^{1/2}$$

## The Continuity Argument

- ◆ Again, two steps:
  - Show that the last 4 estimates follow from the first.
  - Show that the first estimate with the constant halved follows from the 5 estimates.
- ◆ For the second step, we must use the extra decay that follows from the null condition.

## Key Innovation

- ◆ Establishing the energy estimates without the convenient assumption of star-shapedness.
- ◆ Allowing for the loss of derivative in the local energy decay.

## Global Existence for (4)

- ◆ Suppose that the local energy decay estimate (E) holds and that the null condition (N2) holds. Then, there is a global solution to (4) for sufficiently small data  $f, g$ . [M.-Nakamura-Sogge (2003)]

## Another Continuity Argument

- ◆ Three tiered argument... (1) low order energy, (2) pointwise bound on the gradient, (3) higher order energy estimate and weighted mixed norm estimates.

## The Continuity Argument

$$\frac{\sum_{\mu+\alpha \leq 52, \mu \leq 2} \|L^\mu Z^\alpha u'(t, \cdot)\|_2 \leq A_0 \varepsilon}{(1+t+|x|) \sum_{|\alpha| \leq 40} \|Z^\alpha u'(t, x)\| \leq A_1 \varepsilon} \\ \frac{\sum_{|\alpha|+\nu \leq 55, \nu \leq 3} \|L^\nu Z^\alpha u(t, x)\| \leq B_1 \varepsilon^2 (1+t)^{1/10} \log(2+t)}{\sum_{|\alpha| \leq 100} \|\partial^\alpha u'(t, \cdot)\|_2 \leq B_2 \varepsilon (1+t)^{1/40}} \\ \sum_{|\alpha|+\nu \leq 65, \nu \leq 4} \|L^\nu Z^\alpha u'(t, \cdot)\|_2 \leq B_3 \varepsilon (1+t)^{1/20}} \\ \sum_{|\alpha|+\nu \leq 62, \nu \leq 4} \|\langle x \rangle^{-1/2} L^\nu Z^\alpha u\|_{L_t^2 L_x^2(S_t)} \leq B_4 \varepsilon (1+t)^{1/20} (\log(2+t))^{1/2}$$

## The Pointwise Estimate

- ◆ In order to establish the pointwise estimate in MS, we use an exterior domain analog of

$$(1+t+|x|) |v(t, x)| \leq C \sum_{\mu+\beta \leq 3, \mu \leq 0} \iint_0^t |L^\mu Z^\beta \square v(s, y)| \frac{dy ds}{|y|}$$

- ◆ It is not clear how to use (N2) here.

## Energy Estimate Instead

- ◆ Standard Energy Integral Method...

$$\frac{1}{2} \partial_t |u|^2 - \operatorname{div}_x (\partial_t u \nabla u) = \partial_t u \square u$$

- ◆ Integrate both sides in both  $x$  and  $t$ , and apply the divergence theorem.
- ◆ Use the mixed norm estimate to handle terms on the boundary of the obstacle.

## Weighted Sobolev Estimates

- ◆ To handle the multi-speed terms, we use some weighted Sobolev estimates. These are exterior domain analogs of the following [Klainerman-Sideris, Sideris, Sideris-Tu, Hidano]

$$\begin{aligned} \|(t-|x|)\partial^2 u(t,\cdot)\|_2 &\leq C \sum_{|\alpha|\leq 1} \|\Gamma^\alpha u'(t,\cdot)\|_2 + C \|(t+|x|)\square u(t,\cdot)\|_2 \\ |x|^{1/2} (t-|x|) |\partial u(t,x)| &\leq C \sum_{|\alpha|\leq 2} \|\Gamma^\alpha u'(t,\cdot)\|_2 + C \sum_{|\alpha|\leq 1} \|(t+|x|)\Gamma^\alpha \square u(t,\cdot)\|_2 \end{aligned}$$

## Pointwise Gradient Estimate

- ◆ Trivial in free space since derivatives commute with the d'Alembertian.
- ◆ Not at all trivial in the exterior domain... the spatial derivatives do not preserve the Dirichlet boundary condition.
- ◆ Here we use the assumption that the forcing term is supported in  $|x| < 10t$
- ◆ Then, on  $|x| < t/10$ , we have...

## Pointwise Gradient Estimate

$$\begin{aligned} (1+t+|x|) |L^\nu Z^\alpha u'(t,x)| &\leq C \sum_{\mu+|\beta|\leq \nu+|\alpha|+3, \mu\leq \nu+1} \int \int |L^\mu Z^\beta \square u(s,y)| \frac{dy ds}{|y|} \\ &\quad + C \sup_{0\leq s\leq t} (1+s) \sum_{\mu+|\beta|\leq \nu+|\alpha|+4, \mu\leq \nu} \|L^\mu Z^\beta \square u(s,\cdot)\|_\infty \\ &\quad + C \sup_{0\leq s\leq t} (1+s) \sum_{\mu+|\beta|\leq \nu+|\alpha|+6, \mu\leq \nu} \int_0^s \int_{\substack{|y|-(s-\tau)\leq 10 \\ |y|\leq (1000+\tau)/2}} |L^\mu Z^\beta \square u(\tau,y)| \frac{dy d\tau}{|y|} \\ &\quad + C \sup_{0\leq s\leq t} (1+s) \sum_{\mu+|\beta|\leq \nu+|\alpha|+7, \mu\leq \nu+1} \int_s^t \int_{|y|\geq (1+\tau)/10} |L^\mu Z^\beta \square u(\tau,y)| \frac{dy d\tau}{|y|} \end{aligned}$$

## Further Studies...

- ◆ Allow the forcing term to contain cubic terms. [In early preparation... M.-Nakamura-Sogge]
- ◆ Global Existence in Higher Dimensions. [In early preparation... M.]
- ◆ Equations of Elasticity in Exterior Domains ???